

Package ‘gym’

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Version 0.1.0

Title Provides Access to the OpenAI Gym API

Description OpenAI Gym is a open-source Python toolkit for developing and comparing reinforcement learning algorithms. This is a wrapper for the OpenAI Gym API, and enables access to an ever-growing variety of environments.

For more details on OpenAI Gym, please see here: <<https://github.com/openai/gym>>.

For more details on the OpenAI Gym API specification, please see here:

<<https://github.com/openai/gym-http-api>>.

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URL <https://github.com/paulhendricks/gym-R>

BugReports <https://github.com/paulhendricks/gym-R/issues>

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create_GymClient	<i>Create a GymClient instance.</i>
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Description

This function instantiates a GymClient instance to integrate with an OpenAI Gym server.

Usage

```
create_GymClient(remote_base)
```

Arguments

remote_base The URL of the OpenAI gym server. This value is usually "http://127.0.0.1:5000".

Value

An instance of class "GymClient"; this object has "remote_base" as an attribute.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)

## End(Not run)
```

`env_action_space_contains`

Evaluate whether an action is a member of an environments's action space.

Description

Evaluate whether an action is a member of an environments's action space.

Usage

```
env_action_space_contains(x, instance_id, action)
```

Arguments

<code>x</code>	An instance of class "GymClient"; this object has "remote_base" as an attribute.
<code>instance_id</code>	A short identifier (such as "3c657dbc") for the environment instance.
<code>action</code>	An action to take in the environment.

Value

A boolean atomic vector of length one indicating if the action is a member of an environments's action space.

Examples

```
## Not run:  
remote_base <- "http://127.0.0.1:5000"  
client <- create_GymClient(remote_base)  
env_id <- "CartPole-v0"  
instance_id <- env_create(client, env_id)  
action <- env_action_space_sample(client, instance_id)  
env_action_space_contains(client, instance_id, action)  
  
## End(Not run)
```

`env_action_space_info` *Get information (name and dimensions/bounds) of the environments's action space.*

Description

Get information (name and dimensions/bounds) of the environments's action space.

Usage

```
env_action_space_info(x, instance_id)
```

Arguments

x An instance of class "GymClient"; this object has "remote_base" as an attribute.
instance_id A short identifier (such as "3c657dbc") for the environment instance.

Value

A list containing "name" (such as "Discrete"), and additional dimensional info (such as "n") which varies from space to space.

Examples

```
## Not run:  
remote_base <- "http://127.0.0.1:5000"  
client <- create_GymClient(remote_base)  
env_id <- "CartPole-v0"  
instance_id <- env_create(client, env_id)  
env_action_space_info(client, instance_id)  
  
## End(Not run)
```

env_action_space_sample

Sample an action from the environments's action space.

Description

Sample an action from the environments's action space.

Usage

```
env_action_space_sample(x, instance_id)
```

Arguments

x An instance of class "GymClient"; this object has "remote_base" as an attribute.
instance_id A short identifier (such as "3c657dbc") for the environment instance.

Value

An action sampled from a space (such as "Discrete"), which varies from space to space.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
env_id <- "CartPole-v0"
instance_id <- env_create(client, env_id)
env_action_space_sample(client, instance_id)

## End(Not run)
```

env_close	<i>Flush all monitor data to disk.</i>
-----------	--

Description

Flush all monitor data to disk.

Usage

```
env_close(x, instance_id)
```

Arguments

x An instance of class "GymClient"; this object has "remote_base" as an attribute.
instance_id A short identifier (such as "3c657dbc") for the environment instance.

Value

NULL.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
env_id <- "CartPole-v0"
instance_id <- env_create(client, env_id)
env_close(client, instance_id)

## End(Not run)
```

env_create	<i>Create an instance of the specified environment.</i>
------------	---

Description

Create an instance of the specified environment.

Usage

```
env_create(x, env_id)
```

Arguments

x	An instance of class "GymClient"; this object has "remote_base" as an attribute.
env_id	A short identifier (such as "3c657dbc") for the created environment instance. The instance_id is used in future API calls to identify the environment to be manipulated.

Value

A short identifier (such as "3c657dbc") for the created environment instance. The instance_id is used in future API calls to identify the environment to be manipulated.

Examples

```
## Not run:  
remote_base <- "http://127.0.0.1:5000"  
client <- create_GymClient(remote_base)  
env_id <- "CartPole-v0"  
env_create(client, env_id)  
  
## End(Not run)
```

env_list_all	<i>List all environments running on the server.</i>
--------------	---

Description

List all environments running on the server.

Usage

```
env_list_all(x)
```

Arguments

x	An instance of class "GymClient"; this object has "remote_base" as an attribute.
---	--

Value

A list mapping instance_id to env_id e.g. list("3c657dbc" = "CartPole-v0") for every env on the server.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
env_list_all(client)

## End(Not run)
```

env_monitor_close *Flush all monitor data to disk.*

Description

Flush all monitor data to disk.

Usage

```
env_monitor_close(x, instance_id)
```

Arguments

x An instance of class "GymClient"; this object has "remote_base" as an attribute.
instance_id A short identifier (such as "3c657dbc") for the environment instance.

Value

NULL.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
env_id <- "CartPole-v0"
instance_id <- env_create(client, env_id)
env_monitor_close(client, instance_id)

## End(Not run)
```

env_monitor_start *Start monitoring.*

Description

Start monitoring.

Usage

```
env_monitor_start(x, instance_id, directory, force = FALSE, resume = FALSE)
```

Arguments

x	An instance of class "GymClient"; this object has "remote_base" as an attribute.
instance_id	A short identifier (such as "3c657dbc") for the environment instance.
directory	The directory to write the training data to. Defaults to FALSE.
force	Clear out existing training data from this directory (by deleting every file prefixed with "openaigym"). Defaults to NULL.
resume	Retain the training data already in this directory, which will be merged with our new data. Defaults to FALSE.

Value

NULL.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
env_id <- "CartPole-v0"
instance_id <- env_create(client, env_id)
outdir <- "/tmp/random-agent-results"
env_monitor_start(client, instance_id, outdir, force = TRUE, resume = FALSE)

## End(Not run)
```

`env_observation_space_info`

Get information (name and dimensions/bounds) of the environment's observation space.

Description

Get information (name and dimensions/bounds) of the environment's observation space.

Usage

```
env_observation_space_info(x, instance_id)
```

Arguments

`x` An instance of class "GymClient"; this object has "remote_base" as an attribute.
`instance_id` A short identifier (such as "3c657dbc") for the environment instance.

Value

A list containing "name" (such as "Discrete"), and additional dimensional info (such as "n") which varies from space to space.

Examples

```
## Not run:  
remote_base <- "http://127.0.0.1:5000"  
client <- create_GymClient(remote_base)  
env_id <- "CartPole-v0"  
instance_id <- env_create(client, env_id)  
env_observation_space_info(client, instance_id)  
  
## End(Not run)
```

`env_reset`

Reset the state of the environment and return an initial observation.

Description

Reset the state of the environment and return an initial observation.

Usage

```
env_reset(x, instance_id)
```

Arguments

`x` An instance of class "GymClient"; this object has "remote_base" as an attribute.
`instance_id` A short identifier (such as "3c657dbc") for the environment instance.

Value

The initial observation of the space.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
env_id <- "CartPole-v0"
instance_id <- env_create(client, env_id)
env_reset(client, instance_id)

## End(Not run)
```

env_step

Step though an environment using an action.

Description

Step though an environment using an action.

Usage

```
env_step(x, instance_id, action, render = FALSE)
```

Arguments

`x` An instance of class "GymClient"; this object has "remote_base" as an attribute.
`instance_id` A short identifier (such as "3c657dbc") for the environment instance.
`action` An action to take in the environment.
`render` Whether to render the environment. Defaults to FALSE.

Value

A list consisting of the following: `action`; an action to take in the environment, `observation`; an agent's observation of the current environment, `reward`; the amount of reward returned after previous action, `done`; whether the episode has ended, and `info`; a list containing auxiliary diagnostic information.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
env_id <- "CartPole-v0"
instance_id <- env_create(client, env_id)
action <- env_action_space_sample(client, instance_id)
env_step(client, instance_id, action)

## End(Not run)
```

get_request	<i>Submit a GET request to an OpenAI Gym server.</i>
-------------	--

Description

Submit a GET request to an OpenAI Gym server.

Usage

```
get_request(x, route, data = NULL)
```

Arguments

x	An instance of class "GymClient"; this object has "remote_base" as an attribute.
route	The URL path or endpoint.
data	URL query arguments. Default value is NULL.

Value

If the response code is 200 or 204, a parsed response. Else, a server error or raised exception.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
route <- "/v1/envs/"
get_request(client, route)

## End(Not run)
```

gym	<i>gym: Provides Access to the OpenAI Gym API</i>
-----	---

Description

gym: Provides Access to the OpenAI Gym API

```
parse_server_error_or_raise_for_status
    Parse the server error or raise for status.
```

Description

Parse the server error or raise for status.

Usage

```
parse_server_error_or_raise_for_status(response)
```

Arguments

response A response object from `httr::POST` or `httr::GET`.

Value

If the response code is 200 or 204, a parsed response. Else, a server error or raised exception.

Examples

```
## Not run:
b2 <- "http://httpbin.org/post"
response <- httr::POST(b2, body = "A simple text string")
parse_server_error_or_raise_for_status(response)

## End(Not run)
```

```
post_request            Submit a POST request to an OpenAI Gym server.
```

Description

Submit a POST request to an OpenAI Gym server.

Usage

```
post_request(x, route, data = NULL)
```

Arguments

x An instance of class "GymClient"; this object has "remote_base" as an attribute.
route The URL path or endpoint.
data URL query arguments. Default value is NULL.

Value

If the response code is 200 or 204, a parsed response. Else, a server error or raised exception.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
route <- "/v1/envs/"
env_id <- "CartPole-v0"
data <- list(env_id = env_id)
post_request(client, route, data)

## End(Not run)
```

print.GymClient	<i>Represent a GymClient instance on the command line.</i>
-----------------	--

Description

Represent a GymClient instance on the command line.

Usage

```
## S3 method for class 'GymClient'
print(x, ...)
```

Arguments

x	An instance of class "GymClient"; this object has "remote_base" as an attribute.
...	Further arguments passed to or from other methods.

Value

x A GymClient instance.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
print(client)

## End(Not run)
```

random_discrete_agent *A sample random discrete agent.*

Description

A sample random discrete agent.

Usage

```
random_discrete_agent(n)
```

Arguments

n The number of discrete action spaces available.

Value

NULL.

Examples

```
agent <- random_discrete_agent(10)
```

shutdown_server *Request a server shutdown.*

Description

Request a server shutdown.

Usage

```
shutdown_server(x)
```

Arguments

x An instance of class "GymClient"; this object has "remote_base" as an attribute.

Value

NULL Currently used by the integration tests to repeatedly create and destroy fresh copies of the server running in a separate thread.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
shutdown_server(client)

## End(Not run)
```

upload	<i>Flush all monitor data to disk.</i>
--------	--

Description

Flush all monitor data to disk.

Usage

```
upload(x, training_dir, api_key = NULL, algorithm_id = NULL)
```

Arguments

x	An instance of class "GymClient"; this object has "remote_base" as an attribute.
training_dir	A directory containing the results of a training run.
api_key	Your OpenAI API key.
algorithm_id	An arbitrary string indicating the particular version of the algorithm (including choices of parameters) you are running.

Value

NULL.

Examples

```
## Not run:
remote_base <- "http://127.0.0.1:5000"
client <- create_GymClient(remote_base)
outdir <- "/tmp/random-agent-results"
upload(client, outdir)

## End(Not run)
```

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